

A Production Inventory Model with Constant Production Rate, Linear Level Dependent Demand and Linear Holding Cost

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Received: 19 January 2022; Accepted: 26 May 2022; Available online (In press): 10 June 2022

ABSTRACT

In this paper, a production inventory model is proposed which considers products with limited *life and a little amount of decay. In real life problem, there are many scenarios that happened in production inventory which were not taken into consideration by Shirajul Islam and Sharifuddin [19], who formulated a production inventory model and considered both the holding cost and the production rate to be constant. They assumed that the demand is a linear level dependent. Their paper has been modified and extended by considering the holding cost to be linearly dependent on time and the demand rate during production is assumed to be smaller than the demand rate after production. The proposed production inventory model is formulated using systems of differential equations including initial and boundary conditions and typical integral calculus were also used to analyze the inventory problems. These differential equations were solved to give the best cycle length of the model to minimize the inventory cost. A mathematical theorem and proof are presented to establish the convexity of the cost function. From the numerical examples giving to illustrate the application of the model, a Newton-Raphson method* has been used to determine the optimal length of ordering cycle to be 0.54814, optimal cycle *time=2.3014 (840days), optimal quantity=32.9675 and total optimal average inventory cost per unit time=18.253 and accompanied by sensitivity analysis to see the effects of the parameter changes.*

Keywords: Boundary and Initial Conditions, Linear Level Dependent Demand, Linear Holding Cost, Optimal Solution, Production Inventory.

1 INTRODUCTION

Recently, the attention of manufacturers and managers of production inventories have been drawn to the effects of deterioration of items in the business word since the inventories or goods that are manufactured undergoes decay with time. All products have limited life and market demand, and as a result the inventories continues to deplete and some, if not all deteriorate. This deterioration affects the inventories by reducing the quality and quantity of the goods produced which courses an increase on inventory cost. When an item degenerates to a state that it's no longer valuable or lost original purpose, then it is said that deterioration has occurred. Fashionable goods or items such as tomatoes, mangoes, bananas, etc degenerate easily during the storage period.

2 LITERATURE REVIEW

Managers of industries have developed some models of inventory production to save some real-life situations. This is done by developing or constructing good inventory models to consider the situation at hand depending on the nature of the demand in the market. The demands are not normally static but fluctuates from time to time. Based on the nature of the demand, managers of inventories decide how much items to manufacture and when to manufacture.

Harris [1], developed an inventory model that presents the famous Economic Order Quantity (EOQ) formula for the first time. Whitin [2], considered fashionable goods for decaying items at the end of period of the storage. Ghare and Schrader [3], developed an (EOQ) inventory model with constant rate of deterioration. They pointed out in their research that the consumption of the deteriorating items was closely related to a negative exponential function of time. Covert and Philip [4], introduced an inventory model which considered some parameters of Weibull distribution to represent the distribution of the deterioration. The model was modified and extended by Philip [5], considering up to three-parameter Weibull distribution for deterioration. Shah and Jaiswal [6], developed and discoursed an order level inventory model for deteriorating items for constant rate. Aggarawa [7], studied the model of Shah and Jaiswal [6] by correcting the error in it to calculate the average inventory holding cost. The demand rate and the deterioration rate were constant in all the models, also, the replenishment rate was infinite and there was no shortage allowed in inventory. Dave and Patel [8], considered an inventory model for decaying items with time proportional demand, but the demand was taken to be stock dependent and having linear trend. Deb and Chaudhuri [9], studied a model with finite rate of production and a time proportional deterioration rate, following backlogging. Rafaat [10], further review the work of Deb and Chaudhuri [9] by taken into consideration details information that governed the modeling inventory for deteriorating items. Goswami and Chaudhuri [11] also, further extended the model to include the demand rate, production rate and deterioration rate to be all function of time. Jalan and Chaudhuri [12], developed an order model of inventory for degenerating items with no shortages. Teng *et al* [13], studied a model of degenerating items with shortages and they assumed that the demand fluctuates with time positively. Skouri and Papchristos [14], discussed a continuous review inventory model in which there is opportunity cost due to lost sales and replenishment cost due to the linear dependency on the lot size. Ouyang and Cheng [15], discoursed the inventory model for deteriorating items with exponential declining demand and partial backlogging. Chund and Wee [16], developed an integrated two stages production inventory deterioration model for the buyer and the supplier on the basis of stock dependent selling rate considering important items and in time multiple deliveries. Applying inventory replenishment policy, Cheng and Wang [17], discussed an inventory model for deteriorating items with trapezoidal type demand rate which is a piecewise linear function. In the paper, a class of inventory models was developed with time dependent deterioration rate. Kaliraman *et al* [18], discoursed an inventory model of economic production quantity (EPQ) for degenerating items where the deterioration rate was assumed to follow weilbuill distribution with two parameters. The rate of demand was stock dependent and shortages were not allowed. Shirajul Islam and Sharifuddin [19], formulated an inventory model with constant production rate, linear level dependent demand with buffer stock to minimize inventory cost. In their model, they considered the demand to be the same during and after production with a small amount of constant decay. Ali *et al* [20], developed model of an inventory for delay deteriorating items with price and stock depended on demand, fully backlogged shortage and under inflation. The demand function was assumed to be generally dependent on price and stock and when there was shortage then demand would depend only on price of the product. They considered price of the product to be dependent on different kinds

of fixed markup rate and the deterioration was assumed to be non-instantaneous. Shortages were not allowed and fully backlogged. Bashair and Lakdere [21], proposed an EOQ inventory model with backlogging and in the presence of delay deterioration. He argued that the time at which deterioration begins is greater than or equal to the time at which backlogging begins in the basic EOQ model and then the optimal policy was determine by the parameters of basic EOQ model. Swagatika *et al*. [22], contributed in the inventory scenarios of items with instantaneous deterioration. They developed and inventory models for both crisp and fuzzy single commodity with three rates of production where the demand rate was a function of both advertisement and selling price. Dharmendra *et al*. [23], discussed an inventory model for deterioration product for multi-product with partial backlogging to consider carbon emission cost under the influence of inflation. Jamil *et al*. [24], proposed a model of an inventory that considered stock dependent demand allowing few defective items in the model, little amount of decay with constant production rate to find out the total optimum inventory cost, time and ordering cycle.

Motivated by Shirajul Islam and Sharifuddin [19], this paper an inventory model is presented with a linear level dependent demand. The demand during production is assumed to be smaller than the demand after production. There is a small amount of decay during and after production. Our main contribution in this paper is that by considering the holding cost to be linearly dependent on time i.e. $h_{\!\scriptscriptstyle 1}$ + $h_{\!\scriptscriptstyle 2}$ t and the demand rate during production is different from the demand rate after production.

3 ASSUMPTIONS

The production rate λ is always constant and greater than the demand rate. The rate of decay μ is constant and small. Since the decay is small it is assumed that there is no deterioration cost as in Shirajul Islam and Sharifuddin [19]. The demand rate during production at any instant *t* is given by $a + bI(t)$, where a and b are constants and satisfying the condition that $\lambda > a + bI(t)$. The demand rate after production is $\,c+fI\,(t)$ and assumed to be greater than demand during production at any instant t where f and ${\mathsf c}$ are constants. Production starts with little items in the inventory as a safety stock. The inventory level gets to its highest point at the end of production and after which it reduces to the level of the safety stock due to the effects of market demand and degeneration of the items. There are no shortages.

4 NOTATIONS

 $I(t)$ = Stock level at any instance t

 I_{1h} = Holding cost for un-decayed inventory from 0 *to t*₁

 I_{2h} =Holding cost for un-decayed inventory from t_1 *to* T_1

 D_{1h} =Holding cost for deteriorated Inventory from $\,0$ *to t*₁

 D_{2h} =Holding cost for deteriorated Inventory from t_1 *to* T_1

 Q , $\overline{Q}_{\rm l}$ are the sock levels at time $\;$ $\;t$ = $0,\;$ and t= $t_{\rm l}$ respectively. Here ${\rm Q}$ is the safety stock.

dt =Very small portion of instance t
 K_n =Set up cost
 K_n =Set up cost
 K_n =Set up cost
 $\frac{1}{2}$ + $\frac{1}{2}$ + $\frac{1}{2}$ to a average inventory cost per unit
 $T_c = TC(T_i)$ =Total average inventory cost per unit
 T_i =Very small portion of instance *t* K_{ρ} =Set up cost $h_{\!\scriptscriptstyle 1}$ + $h_{\!\scriptscriptstyle 2}$ t =Linear holding cost which is time dependent TC = $TC\big(T_{_I}\big)$ =Total average inventory cost per unit time. *I t* =Time when inventory gets to the maximum level T_I =Total cycle time $Q_{\!\scriptscriptstyle 1}^*$ =Optimal order quantity * t_I^* =Optimal time for a maximum inventory T_I^* =Optimal Order Interval

 $TC\big(T_{\text{l}}\big)^*$ =Optimal average inventory cost per unit time

5 MODEL FORMULATION

The main objective of any business institution is to maximize profit and minimize cost. As a result, all various decisions have to be taken using suitable models. In a production Inventory environment, the demand pattern and production plant dictate the decisions of how and which model to use. The proposed model may be changed to another depending on the situation. In this model, while $t = 0$, the production λ begins from Q inventory and this continues for the whole production cycle. The inventory continues at the rate of $\lambda - a - bI(t) - \mu I(t)$ at $t = 0$ to t_1 . The demand in market is $a + bI(t)$ and $\mu I(t)$ is the deterioration of $I(t)$ inventory at an instance t. From the above information the differential equation of the situation can be formulated as bellow:

Figure 1: Inventory situation before and after production

$$
I(t+dt)-I(t) = \{\lambda-a-bI(t)-\mu I\}dt
$$

\n
$$
\lim_{a\to 0} \frac{I(t+dt)-I(t)}{dt} = \lambda-a-bI(t)-\mu I(t)
$$

\n
$$
\frac{d}{dt}I(t)+\mu I(t) = \lambda-a-bI(t)
$$

\n
$$
\therefore I(t) = \frac{\lambda-a}{\mu+b}+Ae^{-(\mu+b)t}
$$
(1)
\nThis is the differential equation that governed the system.
\nUsing initial /matching condition $I(t) = Q$ at $t = 0$ yields
\n
$$
\therefore A = Q - \frac{\lambda-a}{\mu+b}
$$
(2)
\n
$$
\therefore I(t) = \frac{\lambda-a}{\mu+b} + \left(Q - \frac{\lambda-a}{\mu+b}\right)e^{-(\mu+b)t}
$$
(3)
\nUsing initial /matching condition i.e. at $t = t_1$, $I(t) = Q_1$ taking up to the first degree of μ yields
\n
$$
Q_1 = \frac{\lambda-a}{\mu+b} + \left\{Q - \frac{\lambda-a}{\mu+b}\right\}e^{-(\mu+b)t_1}
$$
(4)
\n
$$
Q_2 = \frac{\lambda-a}{\mu+b} + \left\{Q - \frac{\lambda-a}{\mu+b}\right\} \{1-(\mu+b)t_1\}
$$

\n
$$
= Q + \{\lambda-a-Q\mu-Qb\}t_1
$$

\nUsing equation (3) and considering the total un decayed inventory in the period $t = 0$ to t_1 and ta
\nthe second term of μ yields.
\n
$$
I_{1h} = \int_0^h (h_1 + h_2t) I(t) dt = \int_0^h (h_1 + h_2t) \left[\frac{\lambda-a}{\mu+b} + \left\{Q - \frac{\lambda-a}{\mu+b}\right\}e^{-(\mu+b)t}\right] dt
$$

\n150

This is the differential equation that governed the system.

Using initial /matching condition $I(t)$ = Q at $t = 0$ yields

$$
\therefore A = Q - \frac{\lambda - a}{\mu + b} \tag{2}
$$

$$
\therefore I(t) = \frac{\lambda - a}{\mu + b} + \left(Q - \frac{\lambda - a}{\mu + b}\right) e^{-(\mu + b)t}
$$
\n(3)

Using initial/matching condition i.e. at t = $t_{\rm l}$, $I\big(t\big)$ = $Q_{\rm l}$ taking up to the first degree of μ yields

$$
Q_1 = \frac{\lambda - a}{\mu + b} + \left\{ Q - \frac{\lambda - a}{\mu + b} \right\} e^{-(\mu + b)t_1}
$$
\n(4)

$$
Q_1 = \frac{\lambda - a}{\mu + b} + \left\{ Q - \frac{\lambda - a}{\mu + b} \right\} \left\{ 1 - (\mu + b)t_1 \right\}
$$

= $Q + \left\{ \lambda - a - Q\mu - Qb \right\} t_1$ (5)

Using equation (3) and considering the total un decayed inventory in the period $t = 0$ *to* t_1 and taking the second term of μ yields.
 $I_{1h} = \int_0^{t_1} (h_1 + h_2 t) I(t) dt = \int_0^{t_1} (h_1 + h_2 t) \left[\frac{\lambda - a}{\mu + b} + \left\{ Q - \frac{\lambda - a}{$ the second term of μ yields. $\left[\frac{\lambda-a}{\lambda}+\left\{\mathcal{Q}-\frac{\lambda-a}{\lambda}\right\}e^{-(\mu+b)t}\right]dt$

the second term of
$$
\mu
$$
 yields.
\n
$$
I_{1h} = \int_0^{t_1} (h_1 + h_2 t) I(t) dt = \int_0^{t_1} (h_1 + h_2 t) \left[\frac{\lambda - a}{\mu + b} + \left\{ Q - \frac{\lambda - a}{\mu + b} \right\} e^{-(\mu + b)t} \right] dt
$$

$$
I_{1h} = \left[h_1 \left(\frac{\lambda - a}{\mu + b} \right) t + h_1 \left(Q - \frac{\lambda - a}{\mu + b} \right) \frac{e^{-(\mu + b)t}}{-(\mu + b)} + h_2 \left(\frac{\lambda - a}{\mu + b} \right) \frac{t^2}{2} + \left(Q - \frac{\lambda - a}{\mu + b} \right) \left\{ h_2 t \frac{e^{-(\mu + b)t}}{-(\mu + b)} - h_2 \frac{e^{-(\mu + b)t}}{(\mu + b)^2} \right\} \right]_0^t
$$

$$
= \frac{h_1 (\lambda - a) t_1}{\mu + b} + h_1 \left(Q - \frac{\lambda - a}{\mu + b} \right) \frac{e^{-(\mu + b)t_1} - 1}{-(\mu + b)} + h_2 \left(\frac{\lambda - a}{\mu + b} \right) \frac{t_1^2}{2} + \left(Q - \frac{\lambda - a}{\mu + b} \right) \left\{ \frac{h_2 t_1 \left(e^{-(\mu + b)t_1} - 1 \right)}{-(\mu + b)} - \frac{h_2 \left(e^{-(\mu + b)t} - 1 \right)}{(\mu + b)^2} \right\}
$$

$$
= h_1 Q t_1 + \frac{h_1 Q (\mu + b) t_1^2}{2} - \frac{h_1 (\lambda - a) t_1^2}{2} + \frac{h_2 Q t_1^2}{2} - \frac{h_2 Q (\mu + b) t_1^3}{2} + \frac{Q h_2 t_1}{\mu + b}
$$

$$
= h_1 Q t_1 + \frac{h_1 Q(\mu + b) t_1^2}{2} - \frac{h_1 (\lambda - a) t_1^2}{2} + \frac{h_2 Q t_1^2}{2} - \frac{h_2 Q(\mu + b) t_1^3}{2} + \frac{Q h_2 t_1}{\mu + b} + \frac{h_2 (\lambda - a) t_1^3}{2} - \frac{h_2 (\lambda - a) t_1}{(\mu + b)^2}
$$
\n(6)

Now to calculate the holding cost for deteriorated items as follows:
\n
$$
D_{1h} = \int_{0}^{t_1} \mu(h_1 + h_2 t) I(t) dt = \mu \int_{0}^{t_1} (h_1 + h_2 t) \left[\frac{\lambda - a}{\mu + b} + \left\{ Q - \frac{\lambda - a}{\mu + b} \right\} e^{-(\mu + b)t} \right] dt
$$
\n
$$
D_{1h} = h_1 \mu Q t_1 + \frac{h_1 \mu Q (\mu + b) t_1^2}{2} - \frac{h_1 \mu (\lambda - a) t_1^2}{2} + \frac{h_2 \mu Q t_1^2}{2} - \frac{h_2 \mu Q (\mu + b) t_1^3}{2}
$$
\n
$$
+ \frac{h_2 \mu Q t_1}{\mu + b} + \frac{h_2 \mu (\lambda - a) t_1^3}{2} - \frac{h_2 \mu (\lambda - a) t_1}{(\mu + b)^2}
$$
\n(7)

Also, the inventory changes or reduces on the other side at the rate of $\,c+f\!f\,(t)\!+\mu I\,(t)\,$ at $\,t=t_{_1}$ to $T_{_1}$ as production stop after time t_1 . The demand after production is assumed to be greater than the demand during production. The inventory reduces to the level of safety stock due to effects of degeneration and the market demands of the items. The same procedure is applied also.

$$
I(t+dt) = It + \left\{-c - fI(t)\right\}dt - \mu I(t)dt
$$

\n
$$
I(t+dt - It) = \left\{-c - fI(t) - \mu I(t)\right\}dt
$$

\n
$$
\lim_{dt \to 0} \frac{(t+dt - It)}{dt} = \left\{-c - fI(t) - \mu I(t)\right\}
$$

\n
$$
I(t) = \frac{-c}{\mu + f} + Be^{-(\mu + f)t}
$$
\n(8)

Which is the differential equation that governed the system.

Using initial/matching condition when t = T ₁, $I\left(t\right)$ = Q yields

$$
I(t) = \frac{-c}{\mu + f} + \left(Q + \frac{c}{\mu + f}\right) e^{(\mu + f)(T_1 - t)}
$$
(9)

Using initial /matching condition $I\bigl(t\bigr)=Q_{\!\scriptscriptstyle 1}$ When t = $t_{\scriptscriptstyle 1}$, considering the first term of μ to obtain the equations bellow.

$$
Q_{1} = \frac{-c}{\mu + f} + \left(Q + \frac{c}{\mu + f}\right) e^{(\mu + f)(T_{1} - t_{1})}
$$

= $Q + \left\{c + Q(\mu + f)\right\} (T_{1} - t_{1})$ (10)

Now using Equation (9) to get the holding cost for undecayed inventory during
$$
t = t_1
$$
 to T_1 as
\n
$$
I_{2h} = \int_{t_1}^{T_1} (h_1 + h_2 t) I(t) dt = \int_{t_1}^{T_1} (h_1 + h_2 t) \left[\frac{-c}{\mu + f} + \left\{ Q + \frac{c}{\mu + f} \right\} e^{(\mu + f)(T_1 - t)} \right] dt
$$
\n
$$
= \left[h_1 \left(\frac{-c}{\mu + f} \right) t + h_1 \left(Q + \frac{c}{\mu + f} \right) \left\{ \frac{e^{(\mu + f)(T_1 - t)}}{-(\mu + f)} \right\} + h_2 \left(\frac{-c}{\mu + f} \right) \frac{t^2}{2} + \left(Q + \frac{c}{\mu + f} \right) \right]_{t_1}^{T_1}
$$
\n
$$
= h_1 \left(\frac{h_2 t e^{(\mu + f)(T_1 - t)}}{(\mu + f)} - \frac{e^{(\mu + f)(T_1 - t)} h_2}{(\mu + f)^2} \right)
$$
\n
$$
= h_1 \left(\frac{-c}{\mu + f} \right) (T_1 - t_1) + h_1 \left(Q + \frac{c}{\mu + f} \right) \left\{ \frac{e^{(\mu + f)(T_1 - T_1)} - e^{(\mu + f)(T_1 - t_1)}}{-(\mu + f)} \right\}
$$

$$
\left[\left\{ \frac{a_{2}ie}{-(\mu+f)} - \frac{e^{i\lambda_{1}}}{(\mu+f)^{2}} \right\} \right] \right]_{I_{1}}
$$
\n
$$
= h_{1}\left(\frac{-c}{\mu+f}\right)\left(T_{1}-t_{1}\right) + h_{1}\left(Q + \frac{c}{\mu+f}\right)\left\{ \frac{e^{(\mu+f)(T_{1}-T_{1})} - e^{(\mu+f)(T_{1}-t_{1})}}{-(\mu+f)} \right\}
$$
\n
$$
+ h_{2}\left(\frac{-c}{\mu+f}\right)\left(\frac{T_{1}^{2}-t_{1}^{2}}{2} + \left(Q + \frac{c}{\mu+f}\right)\left[h_{2}\left(T_{1}-t_{1}\right)\left\{ \frac{e^{(\mu+f)(T_{1}-T_{1})} - e^{(\mu+f)(T_{1}-t_{1})}}{-(\mu+f)}\right\} - \left\{ \frac{e^{(\mu+f)(T_{1}-T_{1})} - e^{(\mu+f)(T_{1}-t_{1})}}{(\mu+f)^{2}}\right\}h_{2}\right]
$$
\n
$$
\therefore I_{2h} = h_{1}\left(\frac{-c}{\mu+f}\right)\left(T_{1}-t_{1}\right) + h_{1}Q\left(T_{1}-t_{1}\right) + h_{1}\left(\frac{c}{\mu+f}\right)\left(T_{1}-t_{1}\right) + h_{2}\left(\frac{-c}{\mu+f}\right)\left(\frac{T_{1}^{2}-t_{1}^{2}}{2}\right)
$$
\n
$$
+ h_{2}Q\left(T_{1}^{2}-2T_{1}t_{1}+t_{1}^{2}\right) + \frac{h_{2}Q\left(T_{1}-t_{1}\right)}{\mu+f} + h_{2}\left(\frac{c}{\mu+f}\right)\left(T_{1}^{2}-2T_{1}t_{1}+t_{1}^{2}\right) + \frac{h_{2}c\left(T_{1}-t_{1}\right)}{(\mu+f)^{2}} \qquad (11)
$$

 t_1 to T_1 as below

Multiply equation (11) by
$$
\mu
$$
 above to get the holding cost for determined items during the period
\n t_1 to T_1 as below
\n
$$
D_{2h} = \int_{t_1}^{T_1} \mu(h_1 + h_2 t) I(t) dt = \mu \int_{t_1}^{T_1} (h_1 + h_2 t) \left[\frac{-c}{\mu + f} + \left\{ Q + \frac{c}{\mu + f} \right\} e^{(\mu + f)(T_1 - t)} \right] dt
$$
\n
$$
= h_1 \mu \left(\frac{-c}{\mu + f} \right) (T_1 - t_1) + h_1 \mu Q (T_1 - t_1) + h_1 \mu \left(\frac{c}{\mu + f} \right) (T_1 - t_1)
$$
\n
$$
+ h_2 \mu \left(\frac{-c}{\mu + f} \right) \left(\frac{T_1^2 - t_1^2}{2} \right) + h_2 \mu Q (T_1^2 - 2T_1 t_1 + t_1^2) + \frac{h_2 \mu Q (T_1 - t_1)}{\mu + f}
$$
\n
$$
+ h_2 \mu \left(\frac{c}{\mu + f} \right) (T_1^2 - 2T_1 t_1 + t_1^2) + \frac{h_2 \mu c (T_1 - t_1)}{(\mu + f)^2}
$$
\n(12)

We equate equations (5) and (10) to get the following equations:
\n
$$
Q + \{\lambda - a - Q\mu - Qb\}t_1 = Q + \{c + Q(\mu + f)\}(T_1 - t_1)
$$
\n
$$
\therefore t_1 = \frac{\{c + Q(\mu + f)\}T_1}{c - a + Q(-b + f) + \lambda}
$$
\n(13)

Now let

$$
V = \frac{c + Q(\mu + f)}{c - a + Q(-b + f) + \lambda}
$$
\n(14)

$$
\therefore t_1 = VT_1 \tag{15}
$$

The total average cost per unit time is given as

$$
TC(T_1) = \frac{K_o + I_{1h} + D_{1h} + I_{2h} + D_{2h}}{T_1}
$$
\n(16)

By substituting equations (6), (7), (11), (12), and (15) in equation (16) yields

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\n
$$
\frac{\left[K_a + h_i Q t_1 - \frac{h_i Q(\mu + b) t_1^2}{2} + \frac{h_i (2 - a) t_1^2}{2} + \frac{h_2 Q t_1^2}{2} - \frac{h_2 Q}{2} + \frac{h_2 Q t_1}{\mu + b} + \frac{h_2 (2 - a) t_1^2}{2} + \frac{h_2 \mu Q (1 + b) t_1^2}{2} + \frac{h_2 \mu Q (1 + b) t_1^2}{2} + \frac{h_2 \mu (2 - a) t_1^2}{\mu + b} + \frac{h_2 \mu (2 - a) t_1^2}{2} + \frac{h_2 \mu Q t_1^2}{\mu + b} + \frac{h_2 \mu (2 - a) t_1^2}{2} + \frac{h_2 \mu Q t_1^2}{\mu + b} + \frac{h_2 \mu (2 - a) t_1^2}{2} + \frac{h_2 \mu (2 - a) t_1^2}{\mu + b} + \frac{h_2 \mu (2 - a) t_1^2}{2} + \frac{h_2 \mu (2 - a) t_1^2}{\mu + b} + \frac{h_2 (2 (T_1 - t_1) + h_1 (2 (T_1 - t_1) + h_1 (2 T_1 - t_1) + h_2 (2 T_1 - t_1) + h_2 (2 T_1^2 - T_1^2 t_1 + t_1^2) + \frac{h_2 c (T_1 - t_1)}{(\mu + f)^2} + \frac{h_2 (2 (T_1^2 - 2 T_1^2 t_1 + t_1^2) + \frac{h_2 (2 (T_1 - t_1) + h_1 \mu (2 (T_1 - t_1) + h_1 \mu (2 T_1 - t_1) + h_2 \mu (2 T_1^2 - 2 T_1^2 t_1 + t_1^2) + \frac{h_2 \mu (2 (T_1 - t_1)}{(\mu + f)^2} + \frac{h_2 \mu (2 (T_1 - t_1) + h_2 \mu (2 T_1 - t_1) + h_2 \mu (2 T_1^2 - 2 T_1^2 t_1 + t_1^2) + \frac{h_2 \mu (2 (T
$$

$$
-\frac{n_{2}g(\mu+\nu)(1+\mu)t_{1}}{2T_{1}} + \frac{n_{2}g(\mu+\mu)t_{1}}{(\mu+b)T_{1}} + \frac{n_{2}g(\mu+\mu)t_{1}}{2T_{1}} - \frac{n_{2}g(\mu+\mu)t_{1}}{(\mu+b)^{2}T_{1}} + \frac{h_{1}Q(1+\mu)(T_{1}-t_{1})}{T_{1}} - \frac{h_{2}\left(\frac{c}{\mu+f}\right)(1+\mu)(T_{1}^{2}-t_{1}^{2})}{2T_{1}} + \frac{h_{2}Q(1+\mu)(T_{1}-t_{1})}{(\mu+f)T_{1}} + \frac{h_{2}Q(1+\mu)(T_{1}^{2}-2T_{1}t_{1}+t_{1}^{2})}{T_{1}} + \frac{h_{2}Q(1+\mu)(T_{1}^{2}-2T_{1}t_{1}+t_{1}^{2})}{T_{1}} + \frac{h_{2}c(1+\mu)(T_{1}-t_{1})}{(\mu+f)^{2}T_{1}}
$$

By substituting $t_1 = VT_1$ so that the last equation becomes

$$
TC(T_1) = \frac{K_o}{T_1} + h_1 Q(1+\mu)V - \frac{h_1(\mu+b)(1+\mu)V^2T_1}{2} + \frac{h_2(\lambda-a)(1+\mu)V^2T_1}{2} + \frac{h_2Q(1+\mu)V^2T_1}{2} - \frac{h_2Q(\mu+b)(1+\mu)V^3T_1^2}{2} + \frac{h_2Q(1+\mu)V}{\mu+b} + \frac{h_2(\lambda-a)(1+\mu)V^3T_1^2}{2} - \frac{h_2(\lambda-a)(1+\mu)V}{(\mu+b)^2} + h_1Q(1+\mu)(1-V) - \frac{h_2(\frac{c}{\mu+f})(1+\mu)(1-V^2)T_1}{2} + h_2Q(1+\mu)(1-2V+V^2)T_1 + \frac{h_2c(1+\mu)(1-V)}{(\mu+f)^2}
$$

$$
+h_2\left(\frac{c}{\mu+f}\right)\left(1+\mu\right)\left(1-2V+V^2\right)T_1+\frac{h_2Q\left(1+\mu\right)\left(1-V\right)}{\left(\mu+f\right)}\tag{17}
$$

The main objective is to find the value of $T_{\rm l}$ which gives the minimum variable cost per unit time. The necessary and sufficient condition to minimize $\mathit{TC}\big(T_1\big)$ are respectively:

$$
\frac{dTC(T_1)}{dT_1} = 0 \text{ and } \frac{d^2TC(T_1)}{dT_1^2} > 0
$$

Now, differentiate equation 17 with respect to
$$
T_1
$$
 as follows:
\n
$$
\frac{dTC(T_1)}{dT_1} = -\frac{K_o}{T_1^2} - \frac{h_1(\mu+b)(1+\mu)V^2}{2} + \frac{h_2(\lambda-a)(1+\mu)V^2}{2} + \frac{h_2Q(1+\mu)V^2}{2} - h_2Q(\mu+b)(1+\mu)V^3T_1 + h_2(\lambda-a)(1+\mu)V^3T_1
$$
\n
$$
-\frac{h_2(\frac{c}{\mu+f})(1+\mu)(1-V^2)}{2} + h_2Q(1+\mu)(1-2V+V^2)
$$
\n
$$
+h_2(\frac{c}{\mu+f})(1+\mu)(1-2V+V^2)
$$
\n(18)

This is now equated to zero so as to obtain the T_1 which reduces the cost function.

Theorem 5.1: If $Q(\mu+b) < (\lambda-a)$ then the cost function is convex.

Proof: From equation (18), we take the second derivative as follows:
\n
$$
\frac{d^2TC(T_1)}{dT_1^2} = \frac{2K_o}{T_1^3} - h_2Q(\mu+b)(1+\mu)V^3 + h_2(\lambda-a)(1+\mu)V^3
$$
\n(19)

Therefore,
$$
\frac{d^2TC(T_1)}{dT_1^2} > 0
$$
 provided $h_2Q(\mu+b)(1+\mu)V^3 < h_2(\lambda-a)(1+\mu)V^3$

:. $Q(\mu+b) < (\lambda-a)$

Therefore, equation (17) shows that the cost function is convex in T_1 , then there is optimality in T_1 provided $Q(\mu+b){<}(\lambda-a)$ is satisfied.

6 MODEL DEMONSTRATION

A numerical illustration is provided to demonstrate the developed model. The values of various parameters are as follows: K_o= $\text{\textsterling}100$ Set up cost, λ = 50, Q = 10, h₁ = 3, h₂ = 2, b = 0.4, f = 0.8, μ = 0.01, a = 4 and c = 5. Note that the values of the parameters satisfy theorem 1. Now we substitute the above values of parameters into equations (18) and (19) to compute for T_1 using Newton-Raphson method the solution T_1^* obtained from equations (18) and (19) is now put into equations (5), (15) and (17) to obtain the optimal solution as $Q_1^* = 32.9675$, $t_1^* = 0.54814$, TC(T₁) $^* = 18.45253$ and T₁ $^* =$ 2.3014(840days).

7 EFFECTS OF THE PARAMETER ON THE MODEL

We carefully examine the effects of each parameter K_0 , λ , Q , h_1 , h_2 , b , f , μ , a and c on the optimal length of ordering cycle t_i^* , optimal cycle time T_1^* , optimal quantity Q_1^* and the total average inventory cost $TC(T_1)^*$. The sensitivity analysis is carried out by changing each of the parameters by 50%, 25%, 10%, 5%, -5%, -10%, -25%, -50% taking one parameter at a time and leaving other parameters unchanged.

Table 1: The effects of the parameter changes on the model demonstration 1 to see some changes on the variables of T_1^* , t_1^* , Q_1^* and $TC(T_1)^*$

8 DISCUSSION OF RESULTS

From the results obtained in Table 1, it can be deduced as follows:

The effects of the set up cost, K_0 , on the variables T_1^* , t_1^* , Q_1^* , and $TC(T_1)^*$ is that all increase. This implies that increase in set up cost will result in the increase of the optimal time for maximum inventory t_1^* , optimal cycle time T_1^* , optimal production quantity Q_1^* and total average inventory cost per unit time $TC(T_1)^*$. This is clearly expected since excess stocking is encouraged as a result of high set up cost. The total average inventory cost per unit time $TC(T_1)^*$ is therefore expected to increase due to increase in stocking cost. The variable T_1^* , t_1^* and Q_1^* all increase due to high set up cost as well as stock holding cost.

When there is a change in the value of the production rate λ , the variables T_1^* , t_1^* and $TC(T_1)^*$ reduces while O_1^* increases. This is expected because high production rate leads to shorter cycle time T_1^* especially if the demand rate after production is more than that during production. This will in turn reduce $TC(T_1)^*$. Q_1^* increases since production rate increases.

When the value of the safety stock Q increases, the variables T_1^* reduces while the t_1^*, Q_1^* , and $TC(T₁)$ ^{*} increase. This is because inventory produced takes shorter time to finish hence the optimal cycle T_1^* reduces. On the other hand, the optimal time for maximum inventory t_1^* and optimal quantity Q_1^* increase probably because Q is much. The total average inventory cost is increased due to increase in the holding cost for the safety stock.

The effects of the constant part of the holding cost h₁, the variables T_1^* , t_1^* and Q_1^* remain unchanged while $TC(T_1)^*$ increases. This is because as the demand increases, the optimal average cost $TC(T_1)^*$ increases. On the other hand, the parameter h_1 does not affect optimal time for maximum inventory t_1 ^{*} and optimal quantity Q_1 ^{*} based on equations (13) and (5). They are not very sensitive to h₁.

The stock depended part of the holding cost h_2 increases, the variables T_1^* , t_1^* , Q_1^* , and $TC(T_1)^*$ all reduces. This is expected since if the stock dependent part of the holding cost is higher, the model will force a reduction in the value of the optimal stock Q_1^* . Therefore, T_1^* , t_1^* and Q_1^* will all reduce and this will in turn cause $TC(T_1)^*$ to reduce.

The parameter, a, of the constant part of the demand rate during production increases or changes, while the variables T_1^* , t_1^* and $TC(T_1)^*$ increase while the value of Q_1^* reduces. This is expected since if a is higher, the demand rate is higher and this will increase the optimal cycle time T_1^* , the time for maximum inventory t_1^* as well as the average total cost per unit time TC(T₁)*. Q_1^* reduces probably due to increase in t_1 ^{*}.

When there is change in the value of stock dependent part of the demand during production, the variables T_1^* almost remains unchanged. t_1^* and $TC(T_1)^*$ increase while the value of Q_1^* reduces. Increasing the value of the parameter b, increases the demand and this will in turn increase both T_1^* and the total average inventory cost per unit time. The model will then force a reduction of the optimal production quantity Q_1^* , to reduce stock holding cost.

When there is a change in the value of the parameter c of the constant part of the demand after production, the decision variables T_1^* and $TC(T_1)^*$ reduces while the values of t_1^* and Q_1^* increase. This is expected since if c increases the demand rate increases so Q_1 ^{*} and t_1 ^{*} increase. The high stock

will take less time to finish due to high demand and the total average inventory cost per unit time will reduce.

The value of the parameter d, of the stock dependent demand rate after production changes, the variables t_1 ^{*}and Q_1 ^{*}increase, while the values of $TC(T_1)$ ^{*} reduces. This is expected since if d is higher, the demand rate is higher, and this will increase the optimal cycle time T_1^* though in our case T_1^* is unstable. The time for maximum inventory t_1^* as well as the optimal quantity Q_1^* also increase due to higher demand. Thus the model will seek to lower value of total average inventory cost per unit time $TC(T_1)^*$.

The effects of the change of deterioration rate μ , on the decision variables is that T_1^* reduces while TC(T₁)^{*} and t₁^{*}increase but Q_1 ^{*} is unstable. This is because deterioration forces the model to lower the value of T_1^* . Also due to deterioration, t_1^* will increase so as to make up for what is going to deteriorate. As for $TC(T_1)^*$, it increases due to increase in deterioration cost.

9 CONCLUSION REMARKS

This paper presents a mathematical model of inventory production with constant production rate and linear level dependent demand. The demand during production is assumed to be different from the demand after production even though they are both linear level dependent. There is little amount of constant decay during and after production. A mathematical theorem and proof are presented to show the convexity of the cost function. Also, Newton-Raphson method has been used to determine the optimal solutions of the developed cost minimization model and a numerical illustration is given to demonstrate the application of the developed model. The main objective of the proposed model is to get the optimal length of ordering cycle, optimal cycle time, optimal quantity and total optimal average of the inventory cost per unit time. This paper concludes with notations, assumptions, development of the model, numerical examples and sensitivity analysis.

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